

Objective

This code example demonstrates the implementation of an EZI2C Slave using the PSoC® Creator™ SCB Component on a PSoC 4 device. It also demonstrates how to control the color and intensity of an RGB LED using Timer Counter Pulse Width Modulator (TCPWM) Components.

Overview

This code example implements an I²C Slave using a Serial Communication Block (SCB) Component (configured as EZI2C), which receives the data required to control an RGB LED from an I²C Master. In this example, a host PC running the Cypress Bridge Control Panel (BCP) software is used as an I²C Master. RGB LED control is implemented using three TCPWM Components (configured as PWM). The color and intensity of the RGB LED is controlled by changing the duty cycle of the PWM signals.

Requirements

Tool: PSoC Creator 4.2

Programming Language: C (Arm® GCC 5.4.1 and Arm MDK 5.22)

Associated Parts: PSoC 4 parts

Related Hardware: CY8CKIT-041-40XX, CY8CKIT-041-41XX, CY8CKIT-042, CY8CKIT-042-BLE, CY8CKIT-042-BLE-A, CY8CKIT-044, CY8CKIT-046, CY8CKIT-048, CY8CKIT-149

Hardware Setup

By default, this example project is configured to run on the CY8CKIT-042 development kit from Cypress Semiconductor. The project can be migrated to any supported kit by changing the target device. Open the **Device Selector** from the project's context menu. [Table 1](#) lists supported kits and corresponding devices.

This example uses the kit's default configuration. Refer to the kit guide to ensure that the kit is configured correctly.

Table 1. Supported Kits and Devices

Development Kit	Series	Device
CY8CKIT-041-40XX	PSoC 4000S	CY8C4045AZI-S413
CY8CKIT-041-41XX	PSoC 4100S	CY8C4146AZI-S433
CY8CKIT-042	PSoC 4200	CY8C4245AXI-483
CY8CKIT-042-BLE	PSoC 4200 BLE	CY8C4247LQI-BL483
CY8CKIT-042-BLE-A	PSoC 4200 BLE	CY8C4248LQI-BL483
CY8CKIT-044	PSoC 4200M	CY8C4247AZI-M485
CY8CKIT-046	PSoC 4200L	CY8C4248BZI-L489
CY8CKIT-048	PSoC Analog Coprocessor	CY8C4A45LQI-483
CY8CKIT-149	PSoC 4100S Plus	CY8C4147AZI-S475

Pin assignments for supported kits are provided in [Table 2](#). For these kits, the project includes control files to automatically assign pins with respect to the kit hardware connections during project build. To change pin assignments, override control file selections in the **Pin Editor** of the **Design Wide Resources** by selecting the new port or pin number.

Table 2. Pin Assignments

Development Kit	Pin Assignment				
	I ² C:scl\	I ² C:sda\	LED_Red	LED_Green	LED_Blue
CY8CKIT-041-40XX	P3[0]	P3[1]	P3[4]	P2[6]	P3[6]
CY8CKIT-041-41XX	P3[0]	P3[1]	P3[4]	P2[6]	P3[6]
CY8CKIT-042	P4[0]	P4[1]	P1[6]	P0[2]	P0[3]
CY8CKIT-042-BLE	P3[5]	P3[4]	P2[6]	P3[6]	P3[7]
CY8CKIT-042-BLE-A	P3[5]	P3[4]	P2[6]	P3[6]	P3[7]
CY8CKIT-044	P4[0]	P4[1]	P0[6]	P2[6]	P6[5]
CY8CKIT-046	P4[0]	P4[1]	P5[2]	P5[3]	P5[4]
CY8CKIT-048	P4[0]	P4[1]	P1[4]	P2[6]	P1[6]
CY8CKIT-149	P3[0]	P3[1]	P5[2]	P5[5]	P5[7]

Note: CY8CKIT-149 does not have an RGB LED. Instead, this example controls LED11, LED12, and LED13, which are all green.

Software Setup

For this code example, you need the Bridge Control Panel software, which is installed with PSoC Creator.

Operation

1. Plug your kit board into your computer's USB port.
2. For PSoC 4000S, 4100S, or Analog Coprocessor parts, right click project **EZI2C_Slave_SCB_4S_Analog_Coprocessor** and select **Set As Active Project**.
For all other supported PSoC 4 devices, right click project **EZI2C_Slave_SCB** and select **Set As Active Project**.
3. Build the project and program it into the PSoC 4 device. Choose **Debug > Program**. For more information on device programming, see the PSoC Creator Help.
4. Confirm that the RGB LED is green.
5. Open Bridge Control Panel (**Start > All Programs > Cypress > Bridge Control Panel<Version> > Bridge Control Panel <Version>**).
6. Select the KitProg device in **Connected I2C/SPI/RX8 Ports**. Make sure that the selected protocol is I²C ([Figure 1](#)).
7. Go to **Tools > Protocol Configuration**, and in the **I2C** tab, select **I2C Speed** as **100 kHz**.
8. Press the **List** button and confirm that the EZI2C Slave device with the address 0x08 (7 bits) is available for communication.
9. In the **Editor** tab of the BCP, type the command to send the RGB LED control data, and then click **Send**. Observe that the RGB LED turns ON with the specified color and intensity.

Each command requires writing and reading specific locations of the EZI2C Buffer. For more details on how this buffer is set up, see [Design and Implementation](#).

The packet format for writing to a Slave device from the BCP is shown below.

Start for Write	Slave Address	Slave Buffer Index to Start Write	Red LED TCPWM Compare Value	Green LED TCPWM Compare Value	Blue LED TCPWM Compare Value	Stop
w	(0x08)	(0x00) to (0x02)	(0x00) to (0xFF)	(0x00) to (0xFF)	(0x00) to (0xFF)	p

For example, sending the command 'w 08 00 00 00 00 p' will turn the RGB LED OFF. The command 'w 08 00 FF FF FF p' will turn the RGB LED ON white with full intensity.

You can also control individual LEDs by writing the value to the specific Slave buffer location. For example, sending the command 'w 08 02 7F p' will turn the RGB LED ON with blue color and medium intensity.

You can check the number of write operations that are performed by reading index 0x03 of the Slave buffer. This can be done by setting the write index to the index of the counter, 'w 08 03 p', and then reading that index with 'r 08 x p'.

The packet format for reading data from the Slave device is shown below.

Start for Read	Slave Address	Red LED TCPWM Compare Value	Green LED TCPWM Compare Value	Blue LED TCPWM Compare Value	Number of Write Operations	Stop
r	(0x08)	x	x	x	x	p

For example, sending the command 'r 08 x x x p' will return the last value written to each of the TCPWM Components as well as the number of write operations performed.

For more information on the syntax for Bridge Control Panel commands, go to the Bridge Control Panel help menu and click on the Communication tab in the Contents menu (**Bridge Control Panel > Help Contents > Communication**).

Figure 1. Bridge Control Panel I²C Master Setup

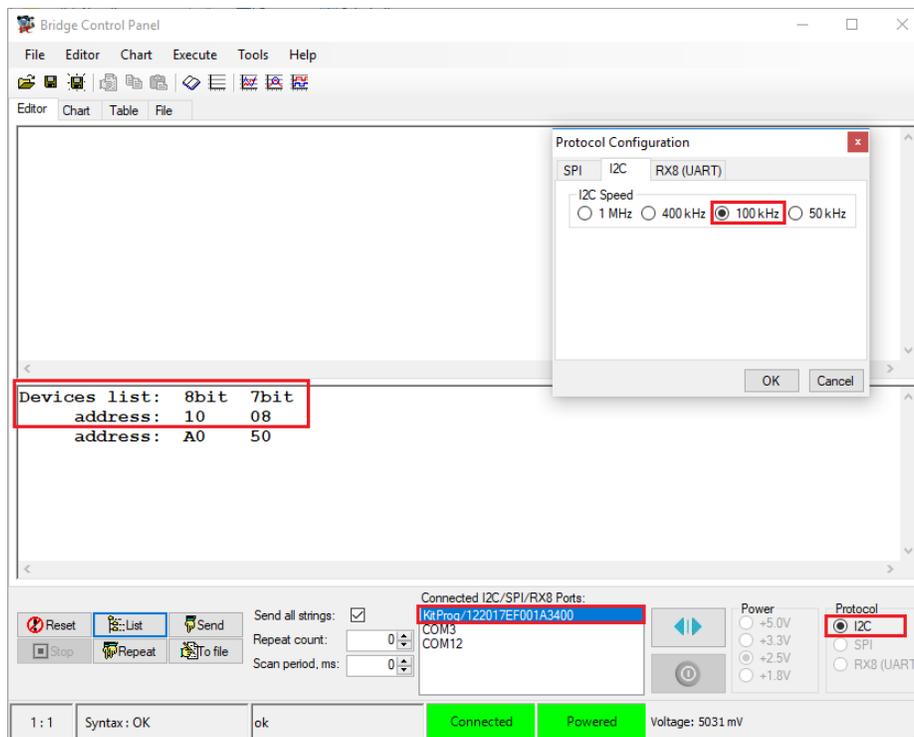
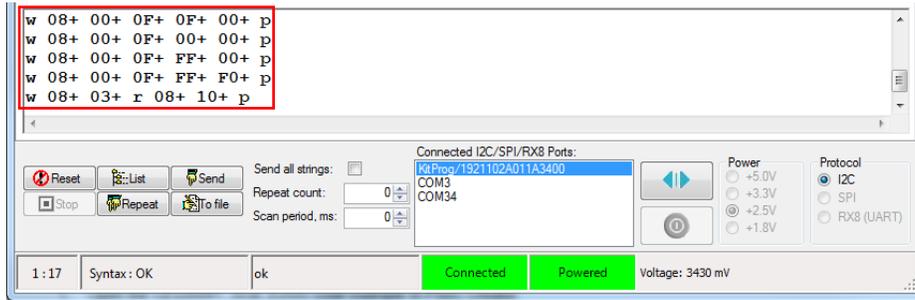


Figure 2. Commands Execution Results

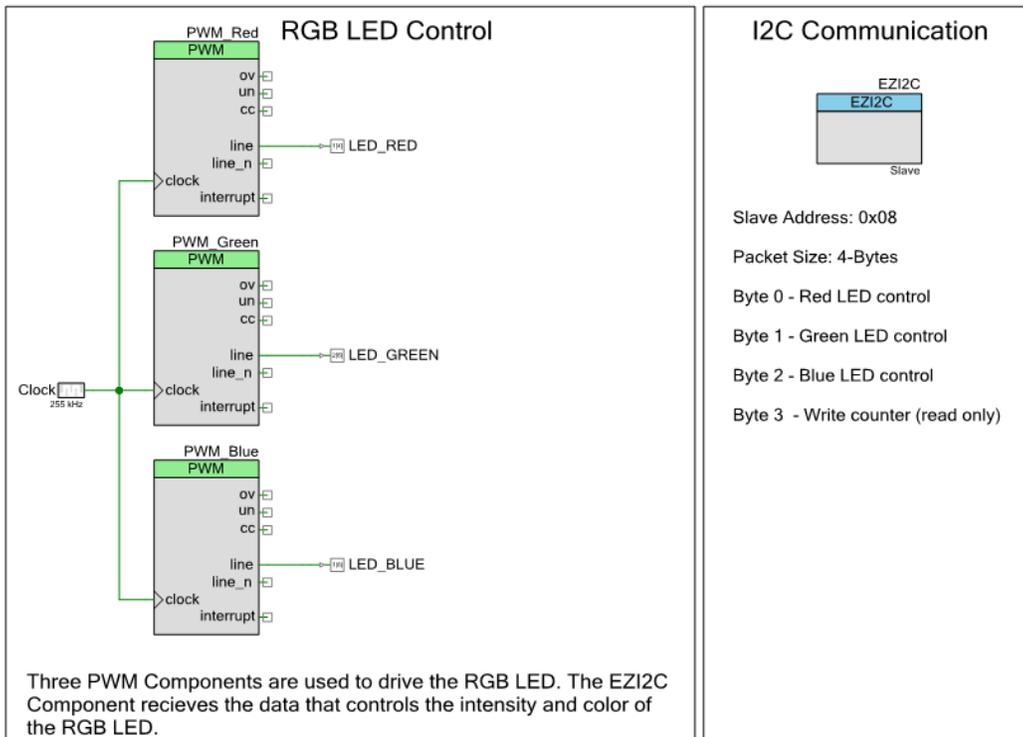


Design and Implementation

The Top Design Schematic of the project is shown in [Figure 3](#).

Figure 3. PSoC Creator Project Schematic

CE95362 - PSoC 4 MCU SCB EZI2C Slave



EZI2C is an implementation of the standard I²C communication protocol in which a single buffer is shared between the Slave device and the Master device. When the buffer is initialized, a writable boundary index is specified. All indices in the buffer that are within the boundary index are writable. All data at or beyond the read/write boundary index is read-only. For example, creating a buffer with a size of 5 bytes and a writable boundary at byte 3 would create the buffer shown below.

Byte 0	Byte 1	Byte 2	Byte 3	Byte 4
Read and Write	Read and Write	Read and Write	Read Only	Read Only

In this example, the EZI2C Component is configured with a 4-byte buffer (memory), which can be accessed by the I²C Master. The first three bytes are writeable and hold the red, green, and blue LED intensity in that order. The fourth byte, which is read-only, holds the number of write operations performed after device reset.

EZI2C allows an I²C Master to either access an individual byte from the Slave memory (by specifying the memory address in the Write command) or all memory bytes at once. For the testing procedure, see [Operation](#).

To control the color and intensity of an RGB LED, three PWMs with period value of 255 (~1 kHz) are used. Duty cycles of the PWMs are controlled in the firmware and specified by the I²C Master. Changing the duty cycle of the PWM signal results in a change in the LED intensity. By changing the intensity of individual LEDs, various colors can be produced on the RGB LED using color mixing. The range of intensity in this example is 0x01 to 0xFF; 0x00 turns the LED OFF. Note that the LEDs on the kit are open-drain devices that are driven low. To compensate for this, the inverting output of each TCPWM Component is used to drive the LEDs.

Components and Settings

[Table 3](#) lists the PSoC Creator Components used in this example, how they are used in the design, and the non-default settings required so they function as intended.

Table 3. PSoC Creator Components

Component	Instance Name	Purpose	Non-default Settings
EZI2C (SCB mode)	EZI2C	Provides I ² C register-based communication with the Master device	Default settings only
Digital Output Pin	LED_RED	Drives the PWM signal to the LED	Default settings only
	LED_GREEN		Default settings only
	LED_BLUE		Default settings only
Clock	Clock	Drives the PWM at 24 MHz	Frequency: 24 MHz
PWM (TCPWM mode)	PWM_Red	Generate square wave and bring out the signal to GPIO	Period: 255 Compare: 0
	PWM_Green		Period: 255 Compare: 0
	PWM_Blue		Period: 255 Compare: 0

For information on the hardware resources used by the Component, see the Component datasheet.

Reusing This Example

This example is designed for the kits shown in [Table 1](#). To port the design to a different PSoC 4 device and/or kit, change the target device using **Device Selector** and update the pin assignments in the **Design Wide Resources Pins** settings as needed.

Related Documents

Application Notes	
AN79953 – Getting Started with PSoC 4	Introduces the PSoC 4 architecture and development tools.
PSoC Creator Component Datasheets	
Pins	Supports connection of hardware resources to physical pins
Serial Communication Block (SCB)	Supports the hardware SCB block
Timer/Counter Pulse Width Modulator (TCPWM)	Supports generation of Pulse Width Modulation signals
Device Documentation	
PSoC 4 Datasheets	PSoC 4 Technical Reference Manuals
Development Kit (DVK) Documentation	
PSoC 4 Kits	

Document History

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Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	6000861	MYKZTMP1	12/28/2017	New code example
*A	6095934	BFMC	03/14/2018	Updated to closely match PSoC 6 EZI2C example Updated template
*B	6162776	BFMC	05/01/2018	Updated Overview section to contain EZI2C Buffer initialization Added Bridge Control Panel Help instructions Added separate project for PSoC 4S-Series and PSoC Analog Coprocessor

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