Introduction to CapSense in ModusToolbox

Bragadeesh Viswanathan Applications Engineer 21st May, 2020



Agenda



- Introduction to CapSense technology
- Self-Capacitance vs Mutual Capacitive sensing
- High Level Hardware Architecture
- > Basic terminologies
- CapSense Tuning
- CapSense Middleware library
- CapSense Configurator in ModusToolbox 2.x
- Demo Project
- CapSense Data Structure
- CapSense Tuner GUI
- Advanced Topics



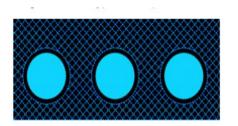
CapSense Technology



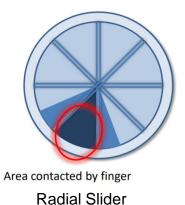
- CapSense technology measures changes in capacitance between a plate (the sensor) and its environment to detect the presence of a finger on or near a touch surface
- Features:
 - Robust touch sensing
 - Liquid tolerant operation
 - Low electromagnetic interference (EMI) performance
 - SmartSense™ Auto-Tuning technology
 - Low power consumption
 - Wide operating voltage range (1.71 V 3.6 V) PSoC 6
 - Proximity sensing

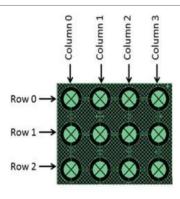
CapSense Sensors



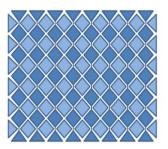


Buttons

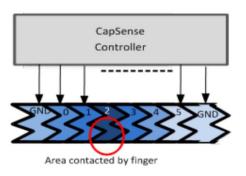




Matrix Buttons



Touchpad/Trackpad



Linear Slider

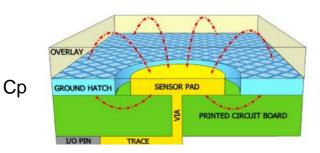


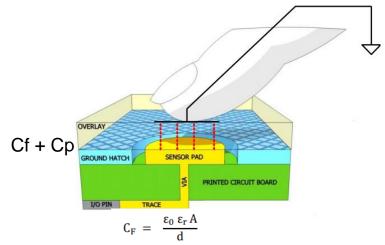
Proximity sensor

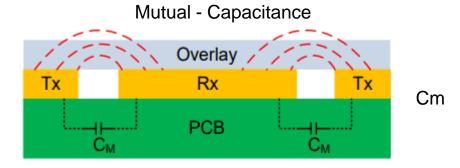
Self Capacitance vs Mutual Capacitance

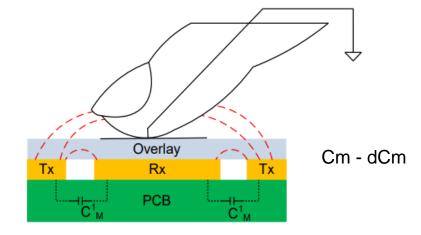


Self Capacitance











When to use CSD, When to use CSX

Parameter/ Requirement	CSD	CSX
Pin constraints	Requires more pins	Requires Less pins(1)
High Cp designs	×	✓
Proximity sensing	✓	×
Overlay thickness	Thick overlays	Thin overlays (1 - 4 mm)
Liquid tolerance	✓	√ (2)
Multi touch performance in matrix buttons	× (3)	✓
Spring sensors	✓	×
VDD noise	√ (4)	×

⁽¹⁾ If sensors required is greater than 7. If there are X * Y sensors requirement, CSX requires only X + Y GPIO whereas CSD requires X * Y GPIO

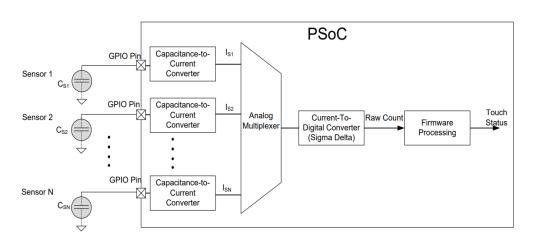
⁽²⁾ CSX + CSD for liquid tolerance. It is a special firmware. Contact our community support for further information.

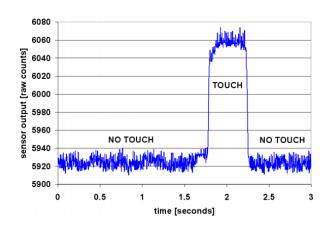
⁽³⁾ Ghost touch – (wrong reporting of fingers upon multi-touch)

⁽⁴⁾ IDAC sourcing mode

CapSense block - CSD







- Each GPIO has a switched-capacitance circuit that converts the sensor capacitance into an equivalent current
- An analog multiplexer then selects one of the currents and feeds it into the current to digital converter
- The current to digital converter is similar to a sigma delta ADC. The output count of the current to digital converter, known as raw count, is a digital value that is proportional to the self-capacitance between the electrodes.





RawCounts

 Digital count value that is proportional to the self-capacitance between the electrodes in case of CSD and Mutual capacitance between electrodes in case of CSX

Baseline

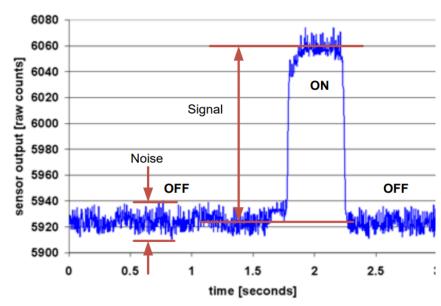
Filtered rawcounts at no touch condition

Difference Counts

 RawCounts(with touch) – Baseline (Signal)

Signal to Noise ratio

 Ratio of CapSense signal to CapSense noise. Recommended SNR is 5 : 1



CapSense Tuning



Why should you tune sensors?

- Reliable touch detection
- Power consumption
- Response time
- Achieving Noise Immunity
- Less Emissions

CapSense Tuning – SmartSense vs Manual Tuning

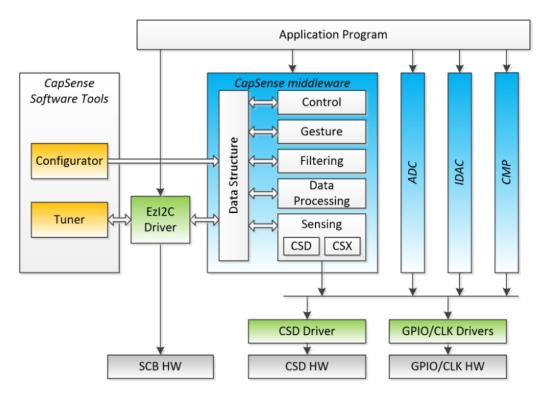


- SmartSense Autotuning:
 - All parameters set by component
 - Reduced design cycle time and easy to use
 - Limitations on memory and supported parasitic capacitance
 - Less control over performance
- Manual Tuning:
 - Strict control over parameter settings such as response time, power consumption and noise immunity.
 - Higher parasitic capacitance designs



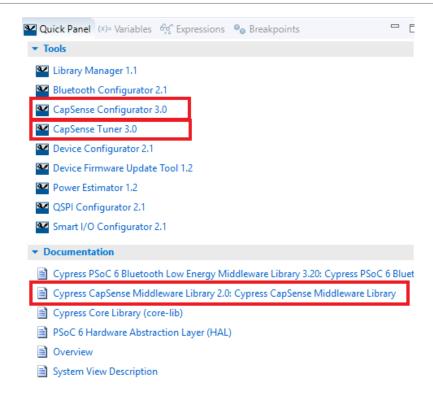


- The CapSense Configurator tool, which is a configuration wizard to create and configure CapSense widgets
- API to control the design from the application program.
- The CapSense Tuner tool for realtime tuning, testing, and debugging, for easy and smooth designing of human interfaces on customer products



CapSense Configurator and CapSense Tuner GUI

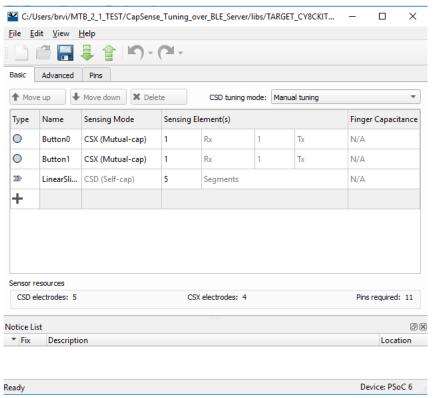




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ame	Date modified	Туре	Size			
bearer	07-Apr-20 3:33 PM	File folder				
docs	07-Apr-20 3:33 PM	File folder				
firmware	07-Apr-20 3:33 PM	File folder				
iconengines	07-Apr-20 3:33 PM	File folder				
imageformats	07-Apr-20 3:33 PM	File folder				
platforms	07-Apr-20 3:33 PM	File folder				
nrintsupport printsupport	07-Apr-20 3:33 PM	File folder				
styles	07-Apr-20 3:33 PM	File folder				
apsense-configurator.exe	25-Mar-20 4:35 AM	Application	14,088 KB			
capsense-configurator.png	25-Mar-20 4:32 AM	PNG File	1 KB			
apsense-configurator-cli.exe	25-Mar-20 4:35 AM	Application	13,476 KB			
apsense-tuner.exe	25-Mar-20 4:36 AM	Application	17,085 KB			
capsense-tuner.png	25-Mar-20 4:32 AM	PNG File	1 KB			
configurator.xml	25-Mar-20 4:32 AM	XML Source File	1 KB			
CyBridge.dll	25-Mar-20 4:36 AM	Application extens	3,504 KB			
libusb-1.0.dll	25-Mar-20 4:36 AM	Application extens	146 KB			
Qt5Core.dll	25-Mar-20 4:36 AM	Application extens	5,986 KB			
Qt5Gui.dll	28-Jan-19 10:45 PM	Application extens	6,308 KB			
Qt5Network.dll	28-Jan-19 10:45 PM	Application extens	1,285 KB			
Qt5PrintSupport.dll	28-Jan-19 10:50 PM	Application extens	311 KB			
Qt5Svg.dll	29-Jan-19 8:51 AM	Application extens	323 KB			
Qt5Widgets.dll	28-Jan-19 10:50 PM	Application extens	5,446 KB			
Qt5XmlPatterns.dll	29-Jan-19 9:26 AM	Application extens	3,240 KB			
version.xml	25-Mar-20 4:32 AM	XML Source File	1 KB			

CapSense Configurator





- Used to create and configure CapSense widgets
- Generate code to control application firmware

Demo Project – CapSense Initialization



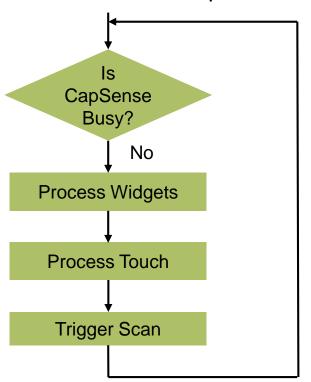
- Include cycfg_capsense.h to include CapSense Middleware and Configurator settings into your project
- Initialize CapSense
 - CapSense interrupt configuration
 - Initialize CapSense hardware
 - Initialize CapSense interrupt
 - Enable CapSense interrupt
 - Initialize CapSense firmware modules

```
/* CapSense interrupt configuration */
const cy_stc_sysint_t CapSense_interrupt config =
    .intrSrc = CYBSP CSD IRQ,
    .intrPriority = CAPSENSE INTR PRIORITY,
};
/* Capture the CSD HW block and initialize it to the default state. */
status = Cy CapSense Init(&cy capsense context);
if(CYRET SUCCESS == status)
    /* Initialize CapSense interrupt */
    Cy SysInt Init(&CapSense interrupt config, capsense isr);
    NVIC ClearPendingIRQ(CapSense interrupt config.intrSrc);
    NVIC EnableIRQ(CapSense interrupt config.intrSrc);
    /* Initialize the CapSense firmware modules. */
    status = Cy CapSense Enable(&cy capsense context);
```



Demo Project – CapSense Scanning and Processing results

Application for ever loop



```
/* Start first scan */
Cy CapSense ScanAllWidgets(&cy capsense context);
for(;;)
    if(CY CAPSENSE NOT BUSY == Cy CapSense IsBusy(&cy capsense context))
        /* Process all widgets */
        Cy CapSense ProcessAllWidgets(&cy capsense context);
        /* Process touch input */
        process_touch();
        /* Start next scan */
        Cy CapSense ScanAllWidgets(&cy capsense context);
```

Demo Project – Check Widget Status

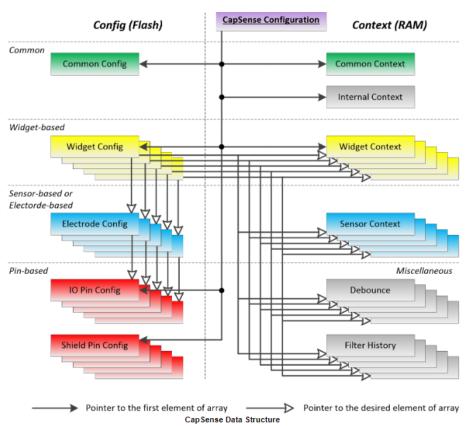


- Cy_CapSense_IsSensorActive()
 - Reports whether the specified sensor in the widget detected touch.
- Cy_CapSense_GetTouchInfo()
 - Reports the details of touch position detected on the specified touchpad, matrix buttons or slider widgets.
- Similar APIs
 - Cy_CapSense_IsWidgetActive()
 - Cy_CapSense_IsProximitySensorActive()
 - Cy_CapSense_IsAnyWidgetActive()

CapSense Data Structure



- The Data Structure is the only data container in the CapSense middleware.
- It serves as storage for the configuration and the output data.
- All CapSense modules use the data sensor-based or structure for the communication and data exchange.
- Data is split between RAM and Flash to achieve a reasonable balance between resources consumption and configuration / tuning flexibility at runtime and compile time





Demo Project – Adding Tuner Support using EZI2C interface

- Initialize an EZI2C interface to communicate with CapSense Tuner GUI
- Expose cy_capsense_tuner structure as the read/ write buffer in EZI2C interface

```
/* Populate slave configuration structure slave config1 */
cyhal ezi2c slave cfg t slave config1 =
        .slave address = SLAVE ADDRESS,
        .buf = (uint8 t *)&cy capsense tuner,\
        .buf size = sizeof(cy capsense tuner),
        .buf rw boundary = sizeof(cy capsense tuner)
};
/* Populate the EZI2C configuration structure */
cyhal ezi2c cfg t ezi2c config =
        .two addresses = false,
        .enable wake from sleep = true,
        .data rate = CYHAL EZI2C DATA RATE 400KHZ,
        .slave1 cfg = slave config1,
        .sub address size = CYHAL EZI2C SUB ADDR16 BITS
/* Initialize EZI2C */
cyhal ezi2c init(&ezi2c obj, P6 1, P6 0, NULL, &ezi2c config);
```



Demo Project – Adding Tuner Support using EZI2C interface

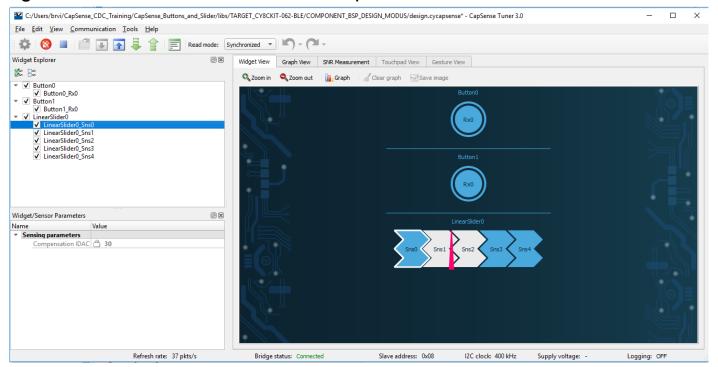
Calling Cy_CapSense_RunTuner() from the application is optional.

```
for(;;)
    if(CY CAPSENSE NOT BUSY == Cy CapSense IsBusy(&cy capsense context))
        /* Process all widgets */
       Cy CapSense ProcessAllWidgets(&cy capsense context);
        /* Process touch input */
        process touch();
        /* Establishes synchronized operation between the CapSense
         * middle ware and the CapSense Tuner tool.
         */
       Cy CapSense RunTuner(&cy capsense context);
        /* Start next scan */
       Cy CapSense ScanAllWidgets(&cy capsense context);
```



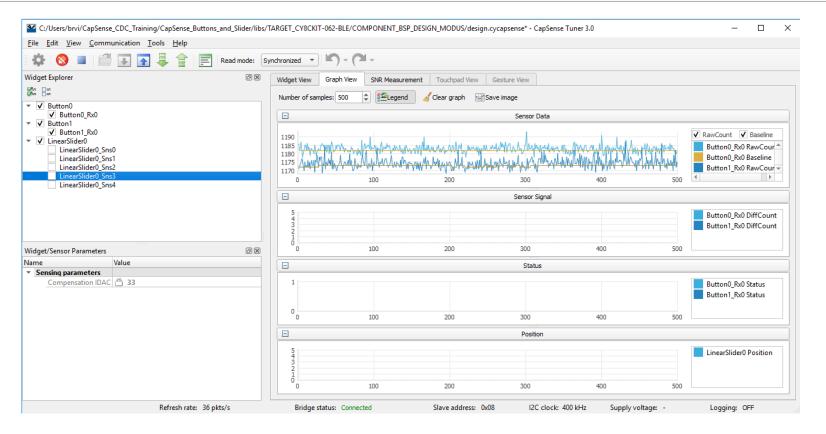


The CapSense Tuner tool for real-time tuning, testing, and debugging, for easy and smooth designing of human interfaces on customer products



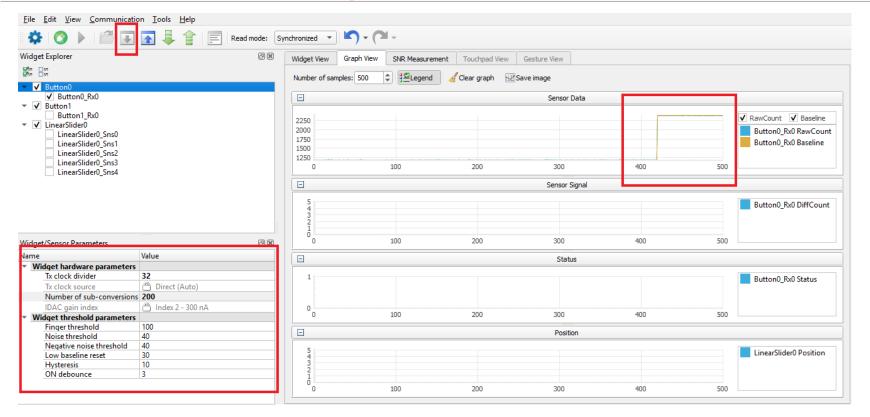


CapSense Tuner GUI – View CapSense raw data



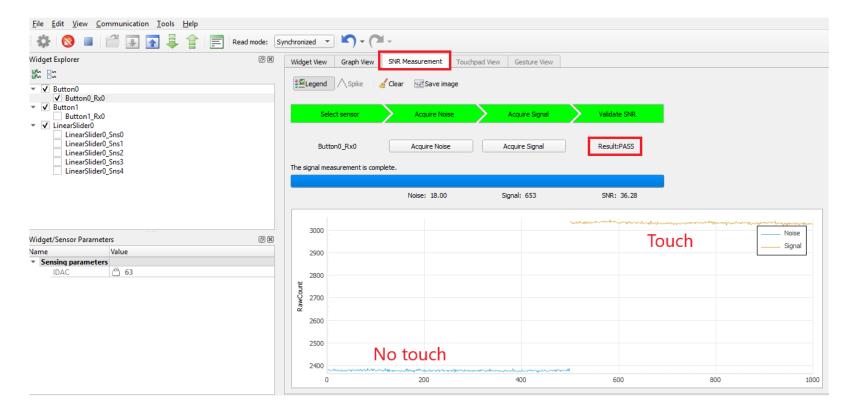


CapSense Tuner GUI – Change hardware/ software parameters





CapSense Tuner GUI – SNR Performance



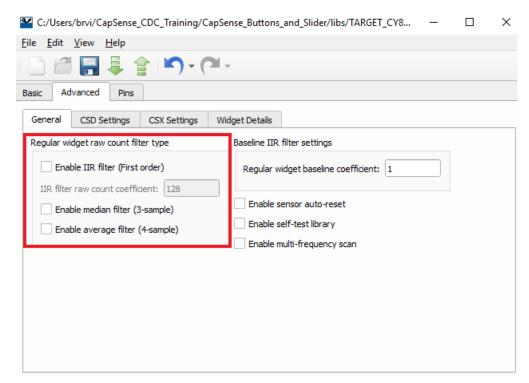
Advanced Topics – Firmware filters



- > IIR filter Eliminates high-frequency noise
- Median filter Eliminates spike noise.
- Average filter Eliminates periodic noise

Limitations:

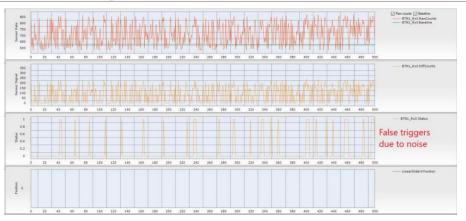
- Increases memory consumption depending on filter
- > IIR filter slows down response
- Increases processing time and hence power consumption

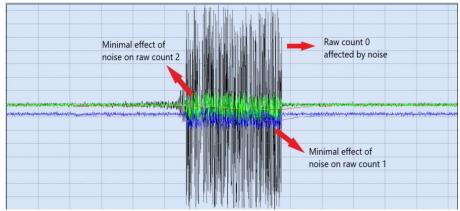




Advanced Topics – Multi Frequency Scanning (MFS)

- MFS is used to prevent false touch detection in the presence of external noise at a particular frequency
- Each sensor is scanned with three different frequencies
- Median filter is applied on the results to eliminate noise





Advanced Topics – Multi Frequency Scanning



- Points to consider when using MFS
 - Enabling MFS increases RAM usage by three times approximately
 - Increases the sensor scan duration by three times
 - The SmartSense (Full Auto-Tune) and the Multi-frequency scan features are mutually exclusive
 - Use CapSense Tuner GUI to view the rawcounts for three different channels.



Advanced Topics – Pipeline scanning using low level APIs

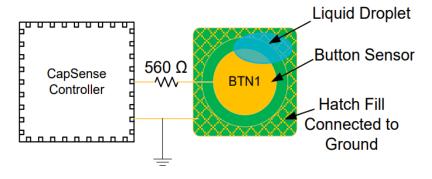
- Custom scanning sequence
- Reduce the total scan/ process time
- Increase the refresh rate
- Decrease the power consumption

```
snsIndex = 0u;
Cy CapSense SetupWidgetExt(CY_CAPSENSE_TOUCHPAD0_WDGT_ID, snsIndex, &cy_capsense_context);/* Trigger scanning */
Cy CapSense ScanExt(&cy capsense context);
for(;;)
    if (CY CAPSENSE NOT BUSY == Cy CapSense IsBusy(&cy capsense context))
        snsIndex++:
        if (snsIndex < cy_capsense_context.ptrWdConfig[CY_CAPSENSE_TOUCHPAD0_WDGT_ID].numSns)</pre>
            /* Trigger the next sensor scanning and process previous sensor */
            Cy CapSense SetupWidgetExt(CY CAPSENSE TOUCHPAD0 WDGT ID, snsIndex, &cy capsense context);
            Cy CapSense ScanExt(&cy capsense context);
            Cy_CapSense_ProcessSensorExt(CY_CAPSENSE_TOUCHPAD0_WDGT_ID, snsIndex,\
                                         CY CAPSENSE PROCESS ALL, &cy capsense context);
        else
            /* The last sensor is scanned already */
            Cy CapSense ProcessSensorExt(CY CAPSENSE TOUCHPAD0 WDGT ID, snsIndex,\
                                   CY CAPSENSE PROCESS ALL, &cy capsense context);
            /* All sensors processed, therefore process only widget-related task */
            Cy CapSense ProcessWidgetExt(CY CAPSENSE TOUCHPAD0 WDGT ID, CY CAPSENSE PROCESS STATUS,\
                                                               &cv capsense context);
            /* Reset sensor index to start from the first sensor */
            snsIndex = 0u:
```

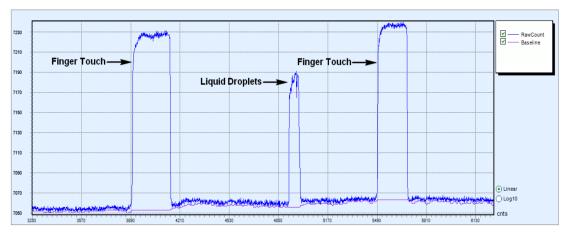
Advanced topics - Liquid tolerance in CapSense designs



When hatch fill around the sensor is grounded, the increase in raw count when a liquid droplet falls on the sensor surface may be equal to the increase in raw count due to a finger touch. In such a situation, sensor false triggers might occur.



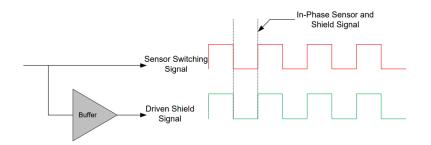


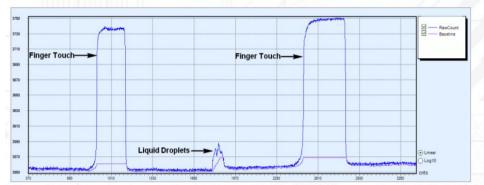




Liquid tolerance in CapSense designs - Shield Electrode

- The driven-shield signal is a buffered version of the sensor-switching signal
- It has the same amplitude, frequency, and phase as that of sensor switching signal
- Buffer provides sufficient current for the driven-shield signal to drive the high parasitic capacitance of the hatch fill
- The increase in raw count when a water droplet falls on the sensor will be very small.





Effect of Liquid Droplet when the Hatch Fill around the Sensor is Connected to the Driven-Shield

Advanced topics – Built in Self Test (BIST)



- Available from CapSense MW 2.10 (to be released soon...)
- HW Tests To confirm the CSD block and sensor hardware (external to chip) function correctly:
 - Chip analog-routing verification
 - Pin faults checking
 - PCB-trace opens / shorts checking
 - Sensors capacitance measurement
 - VDDA measurement.
- FW Tests To confirm the integrity of data used for decision-making on the sensor status
 - Global and widget specific configuration verification
 - Sensor baseline duplication
 - Sensor raw count and baseline are in the specified range.





> Supports one-finger and two-finger gestures on Sliders and touchpad.

Widget Type	Gesture Groups							
	Click	One-finger Scroll	Two-finger Scroll	One-finger Flick	One-finger Edge Swipe	Two-finger Zoom	One-finger Rotate	
Button								
Linear Slider	√	✓		√				
Radial Slider	√							
Matrix Buttons								
Touchpad	✓	✓	✓	✓	√	✓	✓	
Proximity								

Advanced Topics - Gestures



- Use the high level function, Cy CapSense DecodeWidgetGestures() to process all gestures for a specified widget.
- Gesture detection functionality requires a timestamp for its operation. The timestamp should be initialized and maintained in the application program prior to calling this function.
- Call Cy_CapSense_IncrementGestureTimestamp() periodically from the application layer or register a periodic callback such as SysTick to keep the timestamp updated.

Resources



- PSoC® 4 and PSoC 6 MCU CapSense® Design Guide
- Cypress CapSense Middleware Library
- ModusToolbox® Software Environment
- ModusToolbox™ CapSense® Tuner Guide
- ModusToolbox™ CapSense® Configurator Guide
- Code Examples: Github repository



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